

Development of California Regulations to Govern the Testing and Operation of Automated Driving Systems

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Overview

- **Automated Vehicles Levels (Continuum)**
- **Fundamental Regulatory Challenges**
- **Regulatory Issues Considered for Public Roads Testing**
- **Regulatory Issues Considered for Deployment**
- **What's Next?**

SAE J3016 Levels of Automation

Level	Name	Dynamic Driving Steering/Speed	Roadway Monitoring	Fallback Steering/Speed	System Capability
Human Driver Monitors the Driving Environment					
1	Driver Assistance	Driver + System	Driver	Driver	Limitations
2	Partial Automation	System	Driver	Driver	Limitations
System Monitors the Driving Environment					
3	Conditional Automation	System	System	Driver	Limitations
4	High Automation	System	System	System	Limitations
5	Full Automation	System	System	System	Everywhere

Driver Takeover!

Event	Mean PRT	85%
BRT to Tail Lights (1978)		1.6 - 1.9 s
Distracted BRT to FCW (2000)		1.18 s
BRT to Vehicle Pull-Out / Objects (2000)	1.28 - 2.3 s	1.3 - 1.9 s
PRT to Freeway Lane Drop Sign (1990)		3.7 - 6.6 s

- **BMW (2013) – Distracted Driver, Stopped Car Ahead, Takeover**
 - **7 Second Notice → 100% Lane Change**
 - **5 Second Notice → 20% Stopped, Then Lane Change**
 - **Leeds, UK (2014) – Distracted, Unexpected Takeover**
 - **Steering took up to 45 s to really stabilize**
 - **NHTSA L2/L3 Studies (2015)**
 - **Even with short mean PRTs, populations exhibit long tails**
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SAE J3016 Examples

Level	System Description	Examples
Human Driver Monitors the Driving Environment		
1	<u>Driver Assistance</u> <ul style="list-style-type: none"> Adaptive Cruise Control <u>OR</u> Lane Keeping Assistance 	Acura/Honda, Audi, Cadillac/GM, Chrysler, Ford/Lincoln, Hyundai, Infiniti, Lexus/Toyota, Mercedes, Volvo
2	<u>Partial Automation</u> <ul style="list-style-type: none"> Adaptive Cruise Control <u>AND</u> Lane Centering Traffic Jam Assist (Low Speed) Parking Assist 	ACC+LC (LKA/LC may not handle all marking/curves) Acura, Audi, Hyundai, Infiniti, Mercedes GM's Super Cruise (High Speed / Freeway) Cadillac (2017?) Traffic Jam Assist (Low Speed / Freeway) Mercedes (2014), BMW (2014), Audi (2016?)
Automated Driving System Monitors the Driving Environment		
3	<u>Conditional Automation</u> <ul style="list-style-type: none"> Test Vehicles Other Applications Unclear 	Google Lexus Test Cars (2010-Current) Volvo 100-Car Gothenburg Tests (2017?)
4	<u>High Automation</u> <ul style="list-style-type: none"> Driving Pilot (w. Limitations) Closed Campus Driverless Shuttle Driverless Valet Garage Parking 	Long-Term Target for Most Manufacturers Google's Target for 2-Seat NEV Test Vehicle CityMobil2 (Low Speed / Segregated Routes)
5	<u>Full Automation</u> <ul style="list-style-type: none"> Automated Taxi (Even for Children) 	

Fundamental Regulatory Challenges

- Automation blurs the traditional regulatory boundaries
 - NHTSA is responsible for new vehicle equipment & safety
 - States are responsible for vehicle operation (driver licensing)
 - Need to balance:
 - Public Safety while unproven systems are being tested
 - Encouraging Technological Innovation promising improved safety
 - **Lack of technical standards to provide baseline references for performance, safety, or testing protocols or procedures**
 - **Cultural differences between different regulatory agencies, the automotive industry, and the IT industry**
 - **Differing concepts of certification across government agencies, industries, and countries:**
 - Self-Certification vs. Third-Party Certification
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SAE Level 2 Automation Systems: Issues to Consider

- Level 1-2 systems are severely limited by factors not necessarily apparent to drivers
 - lane marking type, curve radius, etc.
- Level 1-2 system can't spot trouble
- Drivers can safely look away from the road
 - How long is too long?
 - Can drivers interact with a phone?
- Misuse (Unknowing)
 - Will the public understand that difference between SAE Level 2 vs. Level 4 System?
- Abuse (Intentional)
 - Leaving the driver's seat
 - Taping a soda can to the steering wheel



2015 Infiniti Q50
ACC+LKA/LC



2015 Mercedes S-Class
ACC+LKA/LC

AV Public Roads Testing Regulations

- **Understanding Testing Characteristics & Goals**
 - **Manufacturer interviews**
- **Administrative Regulations Considered**
 - **Ensuring safety management in the development process**
 - **Prohibition against testing certain vehicles or locations**
 - **Test driver qualifications and training**
 - **Identification or marking of test vehicles**
 - **Crash reporting thresholds**
 - **EDR data specifications & privacy issues**
 - **EDR data usage and program evaluation metrics**

Testing Characteristics & Goals

- Recognize that testing is iterative, changes are frequent, and faults/failures are to be expected
 - Not a linear progression from test track to public roads
 - Minimum testing miles not an indication of readiness
- Safety is achieved through the combination of design, testing policies, and the test driver
 - Test Driver Qualifications & Training
 - Safety Management Process
 - Different levels of system maturity (confidence)
- Prohibiting certain testing locations or vehicle types is counterproductive
- Different testing stages, goals, and protocols
 - Engineering Testing
 - Naïve Driver Testing (Usability, User Experience)
 - Field Operational Testing

Manufacturer Testing Permit Issues: Demonstrating Safety Management

- **Questions We Initially Considered**
 - How many test drivers should be in the vehicle?
 - When is the system ready for more challenging tests and when does the system need to go back to test track testing?
 - What testing protocols are needed to maintain safety?
 - **Safety Management Process**
 - No one-size fits all answer to many safety policy questions
 - Continual risk assessment in decision making
 - Safety Culture - policies and protocols must be followed
 - Potential for 3rd Party Safety Concept Certification
(Bosch received this type of certification from TÜV Süd, 2013)
 - **Test Drivers**
 - Qualifications → minimum equivalent to commercial drivers
 - Training → dependent on system, graduated programs
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Test Vehicle Marking

- **Should You Require AV Test Vehicles Markings?**
 - **Static: Decal or License Plate**
 - **Dynamic: Light**
- **Pros & Cons**
 - Warns other in case test vehicle does something unexpected
 - Test driver is responsible for preventing bad behavior
 - Some cars already easily identifiable...others are not
 - Other road users may treat AV differently (decreasing validity of testing)
 - Marking makes the vehicle a target for fraud or hackers
 - CHP – probably not a need



AV Test Program Performance Metrics

- **How do you evaluate a test permit program's safety?**
 - Crashes
 - Need Exposure
 - Surrogate Safety Metrics (Near Crashes)?
 - EDR Data
- **Crash Reporting**
 - CA VC 16000 requires reporting of crashes (\$750 damage or injuries)
 - Might take time to filter from police reports to DMV
 - Report all crashes (with some minimum threshold)?
 - Report only crashes where AV system active?
 - Report only crashes where AV system active & at fault?
 - **Testing safety relies on (driver + system) → Report all crashes**

EDR Data

- **Surrogate Safety Metrics (Near Crashes)**
 - Many studies analyzing naturalistic data (VTTI 100-Car, SHRP2)
 - Much research on driver monitoring systems (phone apps)
 - Both use combinations of hard accelerations (braking, lateral)
 - **No clear metrics in literature without video analysis (false alarms)**
 - **Hard to catch near misses when the sensors didn't anything**
 - **Should EDR data be submitted to DMV?**
 - Each vehicle will have a different sensor suite & data definitions
 - Standardization difficult, especially during testing phase
 - **Focus on defining a report from manufacturers**
 - CA requiring safety critical disengagements
 - Controversial because disengagements may not indicate safety problems or risky behavior
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AV Public Deployment Regulations

- **Ensuring Safety Prior to Deployment**
 - Behavioral Competency
 - Functional Safety
 - Certification
- **AV Registration and External Marking**
- **Driver Training & Licensing**
- **Cybersecurity & Maintenance**
- **Driverless Operation**

Ensuring Safety: Behavioral Competency

- **Behavioral Competency** describes how well the automation behaves when dealing with external hazards in the normal driving environment.
 - **Why is Behavioral Competency not just an adaptation to the Driving Performance Exam?**
 - **DPE looks at benign conditions (sometimes only urban)**
 - **A basic vehicle control test is going to be easy for an AV manufacturer to tune to perfection: stopping, starting, staying in the lane, obeying traffic laws**
 - **DPE infers potential driving performance potential based on where the driver is looking, sequences of maneuvers, etc.**
 - **AV sensors always looking everywhere they can see, so how do you infer what the system does with that data?**
 - **Safety more related to abnormal condition behavior**
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Behavioral Competency Testing

- **Behavioral Competency could eventually be distilled into performance standards and tests (DMV, NHTSA, SAE, ISO)**
- **Define AV Operating Scenarios:**
 - **Freeway Pilot**
 - **Rural Highway Pilot**
 - **City Street Pilot**
 - **Valet Parking**
 - **Low-Speed Shuttles**
- **Define High-Level Minimum Competencies (Maneuvers)**
 - **Differs by SAE Level of Automation (Assumed Level 3)**
- **Define Test Conditions for Each Competency**
 - **Could be DMV, NHTSA, MFG, SAE/ISO**
 - **NHTSA NCAP FCW Confirmation Test (34 Pages)**
- **Conduct Tests**
 - **Could be DMV, NHTSA, MFG, 3rd Party**

Critical Driving Maneuvers	Freeway	Rural Highway	City Streets	Valet Parking	Low-Speed Shuttles
Detect Operating Envelope & System Malfunctions	✓	✓	✓	✓	✓
Detect & Respond to Speed Limit Changes (Advisory)	✓	✓	✓		✓
Detect Passing and No Passing Zones					
Detect Work Zones, Temporary Lane Shifts, or Safety Officials	✓	✓	✓		
Detect and Respond to Traffic Control Devices		✓	✓		
Detect and Respond to Access Restrictions (one-way, no turn,...)			✓	✓	✓
Perform High Speed Freeway Merge					
Perform a Lane Change or Lower Speed Merge			✓		
Park on the Shoulder (Minimal Risk State)					
Navigate Intersections & Perform Turns			✓		✓
Navigate a Parking Lot & Locate Open Spaces				✓	
Perform Car Following (Including Stop & Go)	✓	✓	✓	✓	
Detect & Respond to Stopped Vehicles	✓	✓	✓	✓	✓
Detect & Respond to Intended Lane Changes / Cut-Ins	✓	✓	✓		
Detect & Respond to Encroaching Oncoming Vehicles		✓	✓	✓	
Detect & Respond to Static Obstacles in Roadway	✓	✓	✓	✓	✓
Detect & Respond to Bikes, Peds, Animals, or Moving Objects		✓	✓	✓	✓
Detect Emergency Vehicles	✓	✓	✓		

Ensuring Safety: Functional Safety

- **Functional Safety** refers to the ability of the automated driving system to accommodate internal hazards & failures, which could be electrical, mechanical, or software.
 - Cannot be evaluated through comprehensive testing
 - Achieved during the design and development using methodologies such as those described in ISO 26262
- ISO 26262 currently relies on the driver as a backup
 - Driver intervention not required in AV Levels 4+
 - Also not entirely considered are interactions between the AV system and driver: Errors, Misuse, and Abuse
 - Efforts to modify ISO 26262 for AVs will take time
- Few avenues to define sensible functional safety regulations, especially in the short term

Ensuring Safety: Certification

- **Self-Certification** used in the US for compliance with FMVSS
 - NHTSA spends about \$11 M / year on compliance testing
 - NHTSA → Broad Investigation, Recall, & Punitive Powers
- **Type Approvals** used outside the US for ADAS & in US by EPA
 - Requires testable standards (e.g., ISO) & an approval body
- **Third-Party Testing** NHTSA NCAP (5-Star Crash Rating) & IIHS
 - NHTSA: \$17.4 M / yr in testing and \$16.6 M / yr in development
 - More appropriate for behavioral competency than functional safety
- **Third-Party Safety Concept Certification** used by EU manufacturers
 - Safety management process during prototype development & testing
- **Third-Party Functional Safety Certification** gaining popularity in EU
 - **Manufacturer correctly following ISO 26262 methodology**

3rd Party Certification Questions

- **What is Being Certified?**
 - Behavioral Competency
 - Functional Safety
- **What is the Depth of the Review?**
 - Driving Test (Benign Conditions)
 - More Comprehensive Testing (Standards, Hazards, Abnormal Conditions)
 - Review of Mfg. Tests & Data
 - Functional Safety Process
 - Functional Safety “Hazard Analysis” by Behavioral Competency Requirement
 - Full Code Review (Aviation)

AV Registration & Driver Licensing

- **AV Registration and External Marking**
 - **Key Registration Issue: Understanding AV capabilities (resale, CHP)**
 - **External Marking: Do the benefits outweigh the cons?**
- **Driver Training and Licensing**
 - **License endorsements proposed/mandated by NV, NJ, other states**
 - **Is the AV driver training universal or vehicle-specific?**
 - **What special knowledge (written test) must be demonstrated?**
 - **What special skills (driving test) must be demonstrated?**
 - **Without an endorsement program, how do drivers get trained?**
 - **Current ADAS owners often unaware of vehicle features**
 - **New Vehicles vs. Used Vehicles vs. Borrowed/Rented Vehicles**
 - **PSA Campaign**
 - **General license testing should exclude AV usage**

AV Cybersecurity & Maintenance

- **Cybersecurity**

- Most vehicle hacking required physical access to vehicle (CAN)
- Tesla website/server hacked, allowing limited access to cars
- 60 Minutes (2015) showed remote hacking a GM Impala over 4G
- Sen. Ed Markey (D-MA) commissioned a report
- No known incidents as of today
- NHTSA will probably need to act for all cars, not just AVs

- **Maintenance**

- System will need to self-diagnose, and prevent activation (faults, failures, or required maintenance)
- Dealers will need to train their staff to repair & calibrate systems
- Similar concerns when hybrids were introduced

- **Focus on Self-Diagnosis Regulation Language**

Driverless Operations Issues

- **Multiple concepts will be driverless**
 - **Valet Parking, Low Speed Shuttles, NEV Taxi**
- **Clear marking such as a special license plate?**
 - **CA CHP wanted some way to quickly identify an unmanned AV vs. runaway vehicle**
- **What is the desired response to emergency vehicles?**
- **Emergency stop (request) for occupants?**
- **Communication to owner/operator for passengers, maintenance, failures, crashes, stuck vehicle, etc.**
- **Owner/operator information exchange post-incident**
- **Restrictions on who can activate or use (children)**

What's Next?

- **Industry standards development proceeding slowly**
 - ISO revisiting 26262 for AVs
 - ISO has both vehicle & HF groups looking at AV issues
 - SAE ORAV (J3016, J3018), S&HF AV Task Force
 - European Commission funded project on AV standards & certification needs prior to deployment
- **Long-term adapting or re-interpreting existing codes**
 - Responding to police, crash monitoring, insurance exchange
 - Penalties for bad driving behavior
 - Restrictions on driver/passenger behaviors (DUI, open alcohol, cell phones, texting, distraction, recklessness...)
 - Protection of unattended children
- **Diversity of state approaches → AAMVA**